CNC-210A Series H6681 User's manual

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1. INTRODUCTION

CNC-210A is a series of COIL WINDING MACHINE CONTROLLER developed by **TAILY AUTOMATION**. It not only retains all the features of previous designs, it also has a low noise level and is less sensitive to external power fluctuation. Furthermore, it also includes a RS-485 network interface, making coil-winding operation easier to manage.

CNC-210A also features an integrated design: putting stepper motor driver, DC motor speed controller, brake and power supplier control circuits into one control box, simultaneously achieving size reduction, high performance and low cost.

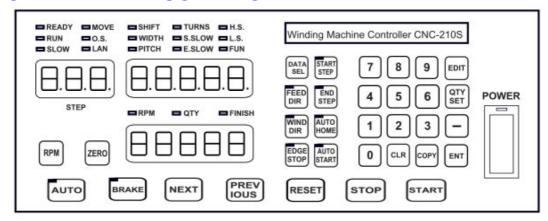
CNC-210A Series offers CNC-210AS "Standard Model" and CNC-210AE "External Connection Model", depending on whether a close-loop driver is provided for various applications.

MODEL	Winding Spindle	Guiding Traverse
CNC-210AS	Drive 0.5hp DC motor in directly.	Drive 2-phase 2A STEP motor in directly.
	External connect winding spindles	Drive 2-phases 2A STEP motor in directly,
L CNC-210AE	motor driver.	Or external connect guiding traverse STEP
		motor driver.

2. MAIN FEATURES

- ◆Single chip Microprocessor design, has further higher performance and higher functions; it also has less sensitive to external power fluctuation or to external electromagnetic interference.
- Memory use FLASH ROM, capacity capable storing up to 1000 steps winding data, 9 winding parameters, and 5 options can be independently assigned for each step. Off-power memory retention without battery.
- Winding speed can be specified using the front panel keypad, resulting in easy programming of multi-step, multi-speed settings.
- Guiding traverse shaft stepper motor with a constant-current driver offering fast wire guiding speeds.
- ◆Guiding traverse shaft offering 10 steps moving speed selection.
- ◆Offering RS-485 interface for PC linking and data transfer.
- ◆ Software can be update through the personal computer.
- ◆Power input AC100V~120V、220V~240V 600VA(max).

3. FRONT PANEL DESCRIPTION



3.1. Power switch

Power supplier equipped, controls the AC power to the controller.

3.2. Key pads

- Em : Enter into EDIT mode.
- (Specify target production quantity.
- START : Specify starting step in memory.
- END: Specify ending step in memory.
- Select item of parameter during edit, or to switch display mode during running.
- Select guiding direction for each step during edit.
- : Select winding direction for each step during edit.
- To specify whether to suspend winding, during the guiding traverse moving to the edges of the width.
- Select whether to have auto-positioning function for each step.
- Select whether to have auto-starting function for each step.
- E : Reduce step number by one, or reduce production counter by one.
- : During programming, clear current data to zero.
- : Copy the data of previous step into current step.
- ENT : Write data into memory.
- : Switch display to shows between production counter and speed (RPM).
- : Hold down this key for two seconds to reset production counter.
- [AUTO]: Switch between automatic and manual mode.
- Switch the brake between lock and unlock during motor stop.
- Skip current step and go to the next step.
- PREV : Discard current step and go to the previous step
- ESST: At any time, discontinues current operation and return to ready mode.
- Pause during winding.
- Restart during pause, or pause during winding.

3.3. Digital display

STEP DISPLAY : Show the current step number being wound or being programmed.

DATA DISPLAY : During programming, in combination with LED, shows

the parameter being programmed. During winding or ready mode, show the current number of turns or show the guiding traverse shafts position.

COUNTER DISPLAY: Shows production counter or RPM.

3.4. Status indicators

☐ **READY**: Lit means in READY mode, flash means PAUSE mode, Not lit means winding or programming in progress.

□ **RUN** : Lit means winding in progress; not lit means not in progress.

☐ **SLOW**: During winding, lit means low speed winding; not lit means high speed winding.

to the home position.

□ **O.S** : Lit means winding operation is over speed, guiding traverse and winding spindle

shaft are out of synchronization.

☐ LAN : Lit means currently are communicating with network.

☐ **FINISH**: Will lit when reaching the preset production counter display count.

☐ **RPM**: Lit means the counter display shows RPM.

QTY: Lit means the counter display shows production counter.

3.5. Winding parameters definitions

SHIFT: Start position of the guiding traverse.

[Setting range 0.00~ 999.99 mm].

WIDTH: Guiding region of the guiding traverse. [Setting range 0 ~999.99 mm].

PITCH: Diameter of the copper wire. [Setting range 0~ 9.999mm].

TURNS: Total number of turns to be wound.

[Setting range 0.0~9999.9 or 0~99999 turns].

S.SLOW: Number of turns to be wound at low speed, when start winding.

[Setting range 0~999.9 turns].

E.SLOW: Number of turns to be done at low speed prior to stopping. [Setting range 0

~999.9 turns].

H.S. : High winding speed. [Setting range from 0~99%].

L.S. : Low winding speed. [Setting range from 0~25%].

FUN: Winding complete output signal setting.

4. PROGRAMMING WINGING PARAMETER

4.1. MEMORY RANGE SELECTION

CNC-210A contains 1000 memory step, by defining the region, users can effectively manage the memory. Various winding parameter can be stored in different regions and can be retrieved instantaneously. After specifying the regions, programming and winding can be done in those regions; all un-selected regions will retain their original contents and unmodified. When setting the STEP number, the Ending step number must be larger than the Starting step number, or the winding operation will not start

- ◆ Specifying starting step
 In ready mode, press START 0~999 ENT to selected. [Setting range 0 ~ 999].
- ◆Specifying ending step
 In ready mode, press to selected. [Setting range 0 ~ 999].

4.2. Programming winding parameter

change.

In READY mode, press invokes the programming mode, the STEP DISPLAY shows START STEP, the parameter indicator SHIFT lit, the DATA DISPLAY shows SHIFT setting value, the SHIFT can be changed by pressing the numerical keys followed by the key.

After that the STEP number will automatically increase by one, to continue set the SHIFT for next step. When the STEP number is larger then the END STEP, the STEP number will restore to the START STEP and the indicator light will change from "SHIFT" to "WIDTH" to specifying the width for each STEP. Repeat the same procedure using numerical keys and the winding parameters for each STEP can thus programmed, after that press key again to go back to ready mode.

back to ready mode.
The following functions are also available:
 To select guiding direction, forward or reverse. To select winding direction, clockwise or counter-clockwise. To specify whether to suspend winding when the guiding traverse moves to the two edges of the width.
: To select whether guiding traverse move to the starting position automatically or upon a manual pressing of the TART key.
Select whether to have auto-starting function for each step.
: Clear the setting value . : Copy the content of the previous step to the current step.
Go back to the previous step. To scroll through different parameters.

Each time when change the parameters and selections, which was pressed to effect the

4.3. Guiding traverse shaft introduce setting

During set the "SHIFT," WIDTH and "guiding traverse travel limit, can use numeric keypad to set location data or can also use [REXT], [REST] keys to leading the guiding traverse shaft location.

4.4. Clear all winding parameter

In the READY mode, press will clear all the winding parameter in the memory. Be cautious in using this function or all the data will be lost.

5. WINDING METHOD DESCRIPTION

Prior to winding, the general winding principles are explained below so the operators can have a better understanding of the performance of the controller and make better use of it.

5.1. Turns counting mode

◆Absolute counting mode

Winding spindle shaft is capable of fixed-point stopping. Upon each restart, the turn count will reset only the integer portion of the turn's to zero, with the decimal unchanged. For example, for a previous number of 100.3 turns, when restarting the next step winding, the counting will start with 0.3 to avoid accumulation of spindle shaft free play error from consecutive windings. This counting method may cause insufficient winding by one turn. Therefore, when starting from **0.9**, the spindle will turn to the **0.0** before it starts counting.

◆Relative counting mode

This counting method zeros the counter upon each restart, therefore it is easy to understand and will not cause insufficient winding.

5.2. Special Wire-guiding mode

◆Interlace wire-guiding

If the "WIDTH of the step is zero, the wire-guiding becomes interlace mode. When it begins winding, the wire-guiding will follow the wire direction to proceed two wire diameters and regress one wire diameters cyclically until the step of winding ends. This mode especially suits the inductor winding.

◆Non wire-guiding

Sometimes, the winding device may be used to winding adhesive tapes or copper foil. When the wire-guiding is not needed, PITCH may be adjusted to zero and the wire-guiding won't be move.

5.3. Start switch operation mode

♦ON-OFF mode

Press down start switch to start winding and release start switch to stop winding immediately.

◆Trigger mode

Press and release start switch once to start winding, press and release start switch again to stop winding

5.4. Running mode

◆Continual mode

Before it begins winding, if "SHIFT of the step set as 999.99, then the starting position, the width, the wire-guiding direction and the winding direction won't be re-read. The values are not changed, that is the wire guiding will continue guiding wires on the same position. The width and left-right margins are the same as the ones of the previous section. Both the wire-guiding and winding directions are not changed either. This mode especially suits to winding which have the multiple drawing tops in the same sets of coils.

◆Edges slow mode

The winding speed will slow down before the guiding traverse reach to the two edges of the width (work with FE. SLOW aturns). After the guiding traverse veered, then restore to hi-speed winding. (Refer to the section 7.1. edge slow mode).

Automatically circularly mode

If will key set to on, it means Automatically circularly mode, in this mode when finish a step of winding it will automatically get into next step and start winding without press start key (work with start and with keys).

5.5. How to set winding turns accurately

◆Preset method

Set the <code>FE.SLOW</code> to zero first and then set the <code>FTURNS</code> to the desired number. Set proper parameters according to copper wire, bobbin, tension, etc, then press to start winding. When finished, obtain the actual number of turns and calculate the number of overshot turns. Go into programming mode and subtract the number of the overshot turns from the <code>FTURNS</code> to obtain the required setting.

This method has a higher throughput, however, the resulting stopping location may not be precise.

◆High-Low speed method

This method uses a combination of <code>"H.S."</code> / <code>"L.S."</code> and <code>"E.SLOW"</code> to achieve the desired number of turns.

The L.S. a should not be too high. The number of E.SLOW aturns must be adequate to allow the spindle shaft to slow down to low speed before reaching the total number of turns. This can result in precise stopping location.

Double-brake method

As the winding turns of the winding shaft reach the numbers of the FESLOW , brake for a short period first. After the winding shaft stops, continue winding at low speed. Therefore the numbers of the slow speed may be reduced and the efficiency of winding may be increased, (Refer to the section 7.1. braking mode).

6. WINDING EXECUTION

6.1. To start winding

After set up all data items, press the winding process begins in accordance with the set-up content. Press to pause winding. During winding, press the key, the winding speed can be switch between high speed and low speed.

The following key functions are available during PAUSE mode:

Give up the numbers of the winding turns and regress one step.

Finish current step and proceed to next step.

START : Continue winding.

Give up winding and go back to the READY mode.

6.2. Change the display mode

During winding or during PAUSE mode, press key, the DATA DISPLAY can be change the display mode between turns or guiding traverse position.

6.3. Winding speed (RPM) display

Pressing key will cause the PIECE COUNT DISPLAY to display the spindle shaft RPM without interrupting the counting. Pressing again will change the PIECE COUNT DISPLAY back to displaying the piece count.

6.4. Production counter management

Upon turning on the power, the counter display will show the production counter. During wining, each time the winding process goes from the START STEP to the END STEP, the counter will automatically increase by one.

◆Preset production counter:

In READY mode, press key once and key in desired values proper followed by the buring winding when the production counter reaches the preset value, the FINISH led will lit. [Setting range 0~99999].

◆Decrease production counter :

During READY or PAUSE mode, press the key and hold down for two seconds the piece counter will decrease by one.

◆Reset production counter:

In any time holding down key for two seconds, it will set the piece counter to zero.

7. CONFIGURATION SETTING

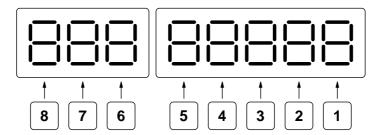
CNC-210A is a multi-purpose design, to meet various requirements; additional settings are configured to provide flexibility for additional applications.

In the READY mode, press the following keys combination as section [7.1. ~7.10], the DATA DISPLAY will show corresponding setting value. If no change is necessary, press the key get back to READY mode. Or press—key to get into change mode, then the parameter can be changed by pressing the numerical key followed by the key.

7.1. Winding mode selection [DIT GATA] 0

In this function the STEP display and the DATA display will shows eight digits, representing eight winding mode selections respectively.

Press numerical keys as below to set each digit.



- Moving speed: The guiding traverse moving speed.
 - **0** represents high speed; **1** represents low speed.
- Moving increment: The travel increment of the guiding traverse.
 - 1 represents 0.01mm (4 mm per revolution).
 - 2 represent 0.02mm (8 mm per revolution).
 - 4 represent 0.04mm(16 mm per revolution.
- **Counting mode:** Select the counting mode of the winding spindle shaft.
 - **0** represents with zero point and using absolute counting mode.
 - 1 represents without zero point and using relative counting mode.
- **Edge slow**: Slow down the winding speed before the guiding traverse reach to the two edges of the width.
 - **0** represents not slow down; **1** represents to slow down.
- **Braking mode**: Select the braking mode of the winding spindle.
 - **0** represents single brake mode; **1** represents double brake mode.
- 6 Counting unit: Select 0.1 or 1 turns as your count unit.
 - **0** represents **0.1**(0.0 to 9999.9 turns); **1** represents **1**(0 to 99999 turns).
- [7] **Guiding traverse unit**: Select the basic unit of guiding traverse.
 - **0** represents **mm**; **1** represents **inch** (must using lead screw in imperial).
- [8] **Operation mode:** Select operation mode for the START switch.
 - **0** represents ON-OFF mode; **1** represents Trigger mode.
 - The start key on the front panel always as the Trigger mode.

7.2. Station number EDIT DATA 1

Set the station number of the winding machine controller. This number is used to identify the station when using RS-485 communication function. Up to 32 stations can be operated on the same network. [Setting range 01~99].

7.3. Password EDIT DATA 2

This password is used to protect the setting data in memory. After you set this password, you cannot change any winding parameter and configuration data in normal sequence. You have to key in four numbers of password before press the [DIT], [STAPT], [STAP

7.4. Travel limit DATA SEL 3

Set the maximum travel distance of guiding traverse. During winding when the guiding traverse reaches this position, the motor stop winding immediately, and the DATA DISPLAY shows error massage, then RESET and go back to the READY mode. [Setting range 000.00~999.99]. 999.99 Means no limit.

7.5. Fixed location [DIT] [DATA 4]

To set how often, must be correct the guiding traverse location. Each time when finish this number of product pieces, the guiding traverse will moves to the home position to correct the location before moving to starting position.

[Setting range 00~ 99]. Set 00 means not to do this function.

7.6. Limited winding speed [DATA] [5]

This value is to limited winding speed and make sure the winding spindle shaft and guiding traverse are in synchronization. The controller uses this value to calculate with wire PITCH of current step, and then to limited maximum winding speed of current step.

[Setting range $0\sim99999$]. Set 0 means no limit speed.

7.7. Brake holding time [DIT] DATA 6

To set the hold times for brake. [Setting range 0.1~9.9 sec].

7.8. Guiding traverse moving speed selection 7

The speed at which the guiding traverse moving to the starting position and returning to the home position. [Setting range 0~9].

7.9. Winding spindle output mode selection [8] 8

Set to "1" for CNC-210AS and CNC-210AE or occur a fault.

7.10. Acceleration times [DIT] DATA 9

Set the accelerate times for the winding spindle [Setting range 00~99].

00 means shortest acceleration times ; **99** means longest acceleration times.

$$T(ms) = (H.S. - L.S.) \times ((N+1) \times 2)$$

7.11. Reset all configuration data of the left of the

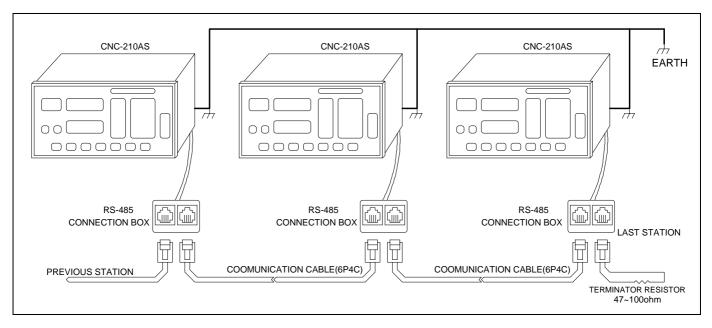
In READY mode press or care of the configuration data and replace by initial data. Be cautious in use this function.

7.12. Data transmit

The CNC-210AS has a RS-485 serial communication interface, can be used to send the winding data to the others station. Up to 32 stations can be operated on the same network.

In this function, set station numbers to the controllers to recognize the controller to which the current data is being sending. (Refer to the section 7.2. station numbers.)

Wiring diagram as below:



In READY mode press following keys combination, its will sent each setting data to target station.

EDT COPY 1 00~99 ENT: Sends winding parameters to the specify station.

EDIT COPY 2 00~99 ENT : Sends password to the specify station.

It will send the winding data from the [START STEP] until to the [END STEP], when sent the winding parameters from one station to another,

Represents target station number. If the target station number specify as "00", all the stations on the same network will receive the data is being sent.

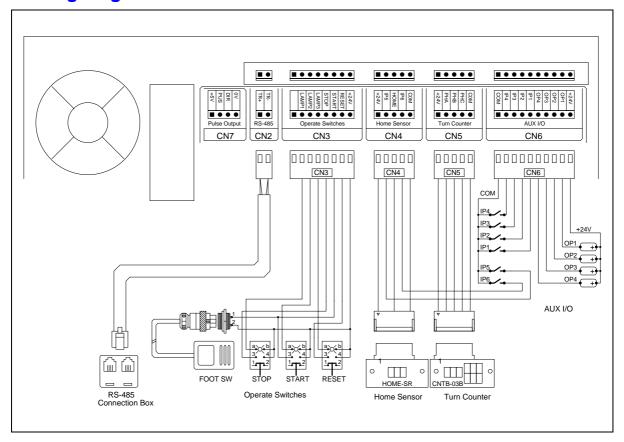
8. INSTALLATION AND WIRING

- ◆The controllers should be operated in an environment that is protected from moisture, corrosive gases, or liquid, and free from airborne dust, metallic particles, and magnetic noise.
- ◆Do not block the intake/exhaust ports of the controller. Otherwise, a fault may occur.
- ◆ Make sure that the power source supplies the correct voltage and is capable of supplying the required current to the controllers.
- ◆ Do not connect or disconnect wires and connectors while power is applied to the controller.
- ◆Make sure the machine and controllers are properly grounded.
- ◆Make sure that the leads and connectors are connected correctly.
- ◆Normally operate under 10 ~ 40 environment; over 40 should perform under good ventilation, avoid heating.

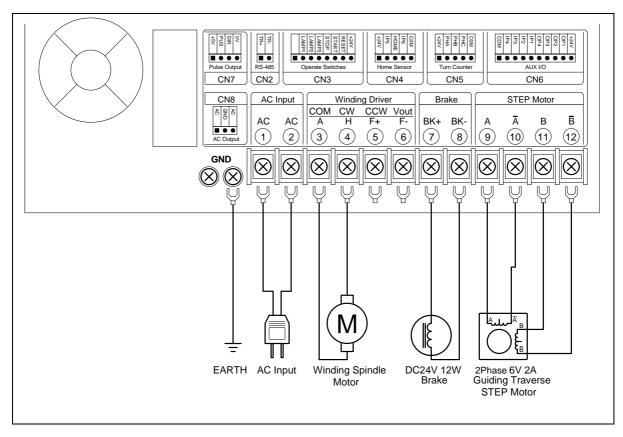
8.1. Accessories and options

	NAME	CNC-210AS	CNC-210AE
210A-CN2 RS-485 Connection box			
210A-CN3 Operate switches connection cable			
210A-CN4	Home sensor connection cable		
210A-CN5	Counting sensor connection cable		
210A-CN6 Aux I/O signal connection cable			
210A-CN7	Pulse output connection cable	×	
210A-CN8	AC output connection cable	×	
HOME-SR	Home sensor		
CNTB-03B/C	Counting sensor		
DISC	Counting disc		
START	Push button switch		
STOP	Push button switch		
RESET	Push button switch		
Foot switch	RUN/STOP Foot switch		
Power cord	AC Power cord		
	= Optional x = not us	se in this model	

8.2. Wiring diagram for CN2~CN6

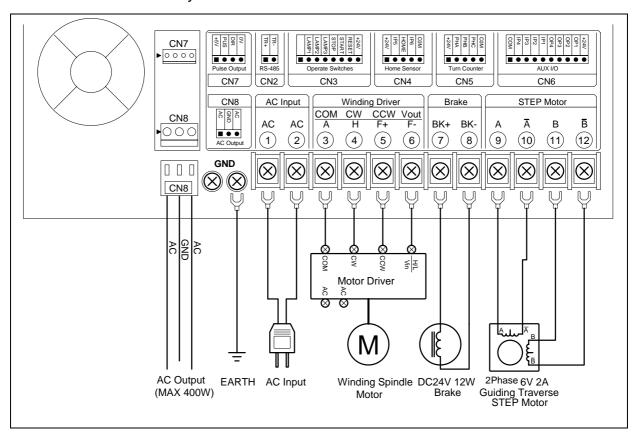


8.3. Wiring diagram for CNC-210AS

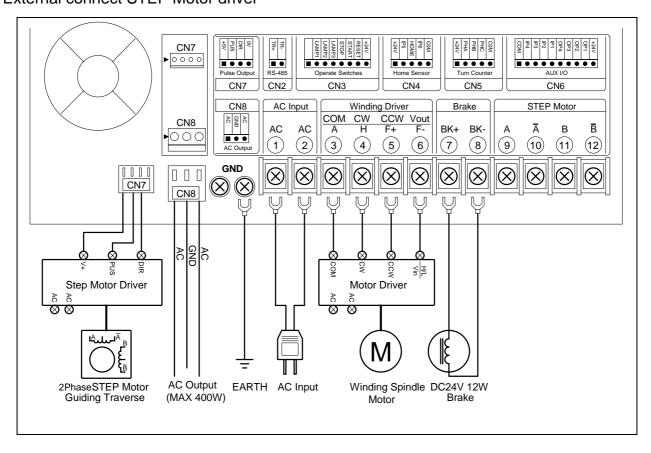


8.4. Wiring diagram for CNC-210AE

◆Drive STEP Motor in directly



◆External connect STEP Motor driver



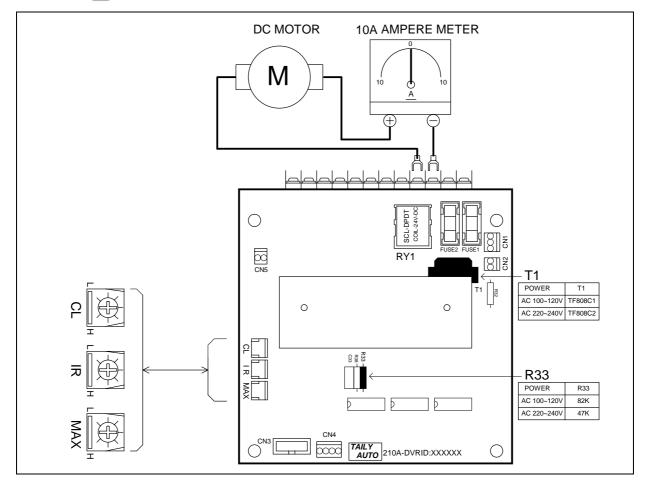
9. ADJUSTMENT

9.1. Adjustments for CNC-210AS

- ◆CL: Output current limit.
- 1. Connect a DC Amperes meter between terminal and DC motor as below.
- 2. In ready mode press rate and then press holding the winding spindle.
- 3. Rotate CL to set limited current, show on Amperes meter. (2A for 180v DC motor、4A for 90v DC motor).

(The CL have been set by factory before delivery. Only adjust it when change DC motor and replace 210A-DVR driver board.)

- ◆IR: Torque compensation.
- 1. Set the winding parameter H.S., L.S. in 20, then press to change the DISPLAY shows RPM. Then press team key to start winding.
- 2. Rotate IR potentiometer to make it in same speed during the winding spindle shaft in full-load and unload. Then press we key to stop winding.
- ◆MAX : Maximum winding speed.
- 1. Set the winding parameter H.S., L.S. in 99, and press key to change the DISPLAY shows RPM. Then press start key to start winding.
- 2. Rotate MAX potentiometer to make the winding speed (RPM) as you want. Then press stop key to stop winding.



9.2. Adjustments for CNC-210AE

◆Speed Mode selection

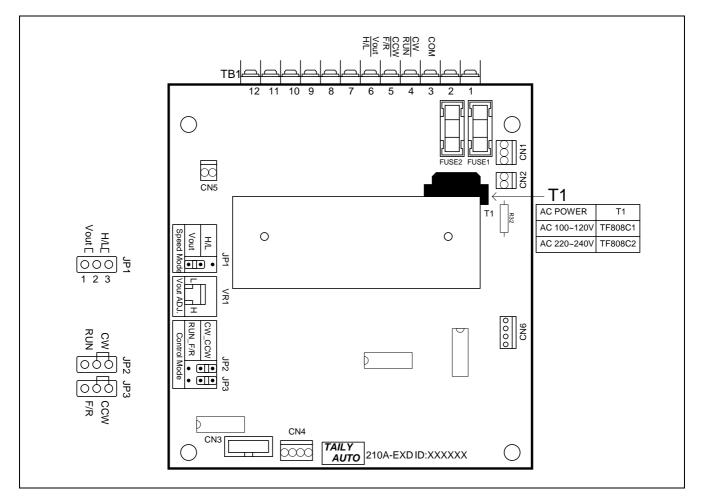
To select the speed signal output mode for winding driver.

Selected by JP1.

- 1. V-out mode: Represents the speed signal with DC 0~10v output.
- 2. H/L mode: Represents the speed signal with HI/LOW lever output. Hi speed with HI lever, low speed with LOW lever.

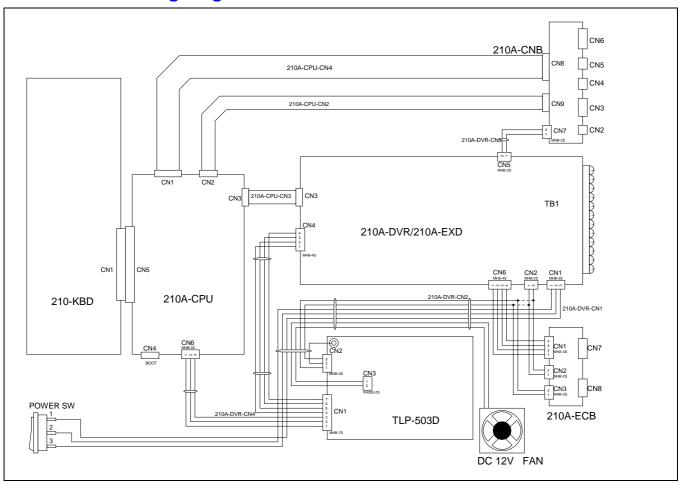
♦V-out adjust

- 1. Set the winding parameter H.S., L.S. in 99, and press key to change the DISPLAY shows RPM. Then press key to start winding.
- 2. Rotate V-out potentiometer to make the winding speed (RPM) as you want. Then press stop key to stop winding.
- 3. This function only worked in Vout mode.



10. MAINTAIN AND TROUBLESHOOTING

10.1. Internal wiring diagram



10.2. Periodically maintain

- ◆Please periodically clean up the controller inner accumulate dust and dopants.
- Please periodically check the wire connection between controller and machine if have loose or bad contact.
- ◆The following parts must be maintained or changed periodically as list below. If any part is found faulty, it must be changed immediately even when it has not yet reached the end of its life, which depends on the operating method and environmental condition.
- ◆ For parts replacement, please contact your sales representative.

NO	Parts name	Life guideline
1	Winding spindles Turns counter CNTB-03B/03C	2 years
2	2 Guiding traverses HOME SENSOR 2 years	
3	COOLING FAN (DC 12V 6cm)	10,000 hours
	RELAY (on the 210A-DVR driver board, it used to switching the winding direction) 100,000 times	
5	Carbon BRUSH of the DC motor	1 year

10.3. Error message

When a fault occurs during operation, the DATA DISPLAY shows error massage, stop winding and then RESET go back to the READY mode.

Err-0: The parameters or data in memory are fault.

Err-1: The SHIFT value sets exceed the Travel Limit.

Err-2: During winding, the guiding traverse to exceed the Travel Limit.

Err-3: During winding, the guiding traverses reach to the Home sensor.

Err-5: RS-485 communication error.

Err-p: Password error, key in 4 numbers password before edit.

10.4. To abort seeks the original position

At boot and reset procedures, if because of unknown reason however engender the winding shaft and guiding traverse can't find out the original position and make the controller can't get into ready mode, can press key to abort seeks the original position, make controller get into ready mode.

10.5. Troubleshooting

This section provides information to guide the user in understanding different fault condition and their general troubleshooting procedures, and with their possible solutions.

- ◆ Do not connect or disconnect wires and connectors while power is applied to the controller.
- ◆ Make sure that the leads and connectors are connected correctly, before doing the troubleshooting procedures.
- ◆Do not remove welded parts on the PC board without appropriate tools.

NO	Fault Description	Correctives Action
1	Power ON, but the display shows nothing.	Check AC power input. Check the LED lamp on TLP-503D power supply, if not lit replace TLP-503D Replace 210A-CPU.
2	Power ON, but the display shows confusion massage,	Replace 210A-CPU.
3	Power ON, but winding spindle didn't rotate, or cannot stop rotation, And controller cannot get into ready mode.	Press to make the controller get into READY mode. Check the winding parameter L.S. setting value of START STEP. Replace turns counter CNTB-03B. Replace 210A-CPU.
4	Power ON, but guiding traverse didn't move or cannot stop moving, And controller cannot get into ready mode.	Press to make the controller get into READY mode. Replace HOME SENSOR. Replace 210A-DVR. Replace 210A-CPU.
5	Cannot edit parameters.	Check the READY LED lamp if not lit, do procedures number 3 and 4.

NO	Fault Description	Correctives Action
		Key in four numbers password before edit, if the password has
		been set before.
		Replace 210-KBD.
		Replace 210A-CPU.
	Display shows Err-0,	Replace 210A-CPU.
6	then reset, and get into	
	READY mode.	
	Display shows	a. Check winding parameters "SHIFT and "WIDTH setting value.b. Check configurations "TRAVEL LIMIT setting value.
7	Err-1/Err-2 then reset	b. Check configurations "TRAVEL LIMIT』 setting value.
'	and get into READY	
	mode.	
	Display shows Err-3,	Check winding parameters 『SHIFT』and 『WIDTH』setting
8	then reset, and get into	value.
	READY mode.	Replace HOME SENSOR.
9	Display shows Err-5.	Check wire connection of RS-485 connection box.
		Check wire connections between two stations.
	Brake failure.	Check wire connections of brake.
10		Replace brake.
		Replace 210A-DVR.
	Winding spindle can	Check configurations F Winding spindle control mode
11	not switching winding	selection a setting value.
	direction.	Replace 210A-CPU.
12	Counting failure.	Replace turns counter CNTB-03B.
		Replace 210A-CPU.
	Guiding traverse moves	Check Configurations Moving increment setting value.
13	half pitch or double	
	pitch.	